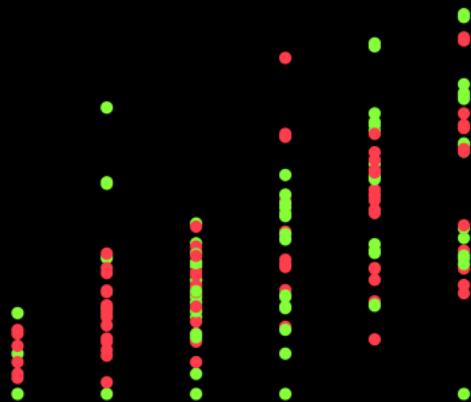


SPECTROSCOPY FOR KNOTS

Bailey Whitbread
University of Sydney



DETECTING THE UNKNOT

Open Problem

*Does the Jones polynomial detect the unknot?
i.e., does $J(K) = J(\text{unknot})$ imply $K \simeq \text{unknot}$?*

$$J: \{\text{Knots \& links}\}_{/\simeq} \rightarrow \mathbb{Z}[q, q^{-1}]$$

$$J\left(\text{unknot}\right) = 1 \quad J\left(\text{trefoil knot}\right) = q^{-1} + q^{-3} - q^{-4}$$

KNOTS AND BRAIDS

Braids are the algebraic analogues of knots

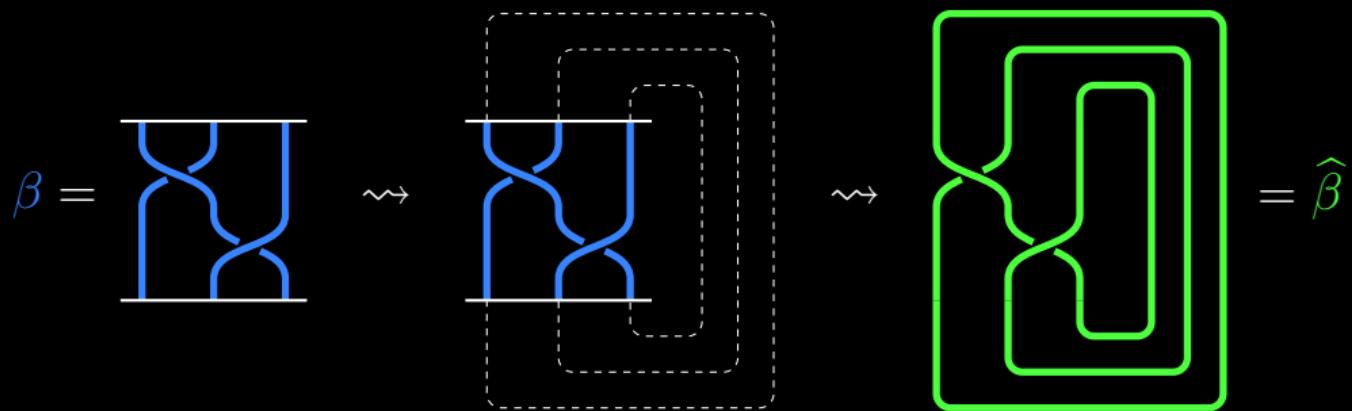
$$B_n = \left\langle \sigma_1, \dots, \sigma_{n-1} : \text{'braid relations'} \right\rangle \quad \sigma_1 = \begin{array}{c} \text{[blue line crossing]} \\ \text{[blue line]} \end{array} \in B_4$$

KNOTS AND BRAIDS

Braids are the algebraic analogues of knots

$$B_n = \left\langle \sigma_1, \dots, \sigma_{n-1} : \text{'braid relations'} \right\rangle \quad \sigma_1 = \begin{array}{c} \text{Diagram of a braid relation} \\ \text{with 4 strands} \end{array} \in B_4$$

A bridge between braids and knots is the braid closure:



THE BURAU REPRESENTATION

Bureau rep.

$$B_4 \rightarrow \mathbf{GL}_3(\mathbb{Z}[v^{\pm 1}])$$

$$B_4 = \left\langle \sigma_1, \sigma_2, \sigma_3 : \begin{matrix} \text{'braid} \\ \text{relations'} \end{matrix} \right\rangle$$

$$\sigma_1 = \overbrace{\text{X}}^1 \overbrace{\text{X}}^2 \mapsto \begin{pmatrix} -v^2 & -v & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$$\sigma_2 = \overbrace{\text{X}}^1 \overbrace{\text{X}}^2 \mapsto \begin{pmatrix} 1 & 0 & 0 \\ -v & -v^2 & -v \\ 0 & 0 & 1 \end{pmatrix}$$

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Theorem (Birman, Bigelow, Ito)

Jones poly.
does not
detect
unknot

\leftrightarrow
Bureau rep.
of B_4 is
unfaithful

The matrices
 $\begin{pmatrix} -v^{-2} & -v^{-1} & 0 \\ 0 & 1 & 0 \\ 0 & -v & -v^2 \end{pmatrix}$ & $\begin{pmatrix} 0 & v^{-3} & v^{-2} \\ 0 & -v^{-2} & v^4 - v^{-1} \\ 1 & v^{-1} & 1 - v^2 \end{pmatrix}$
satisfy a non-trivial relation

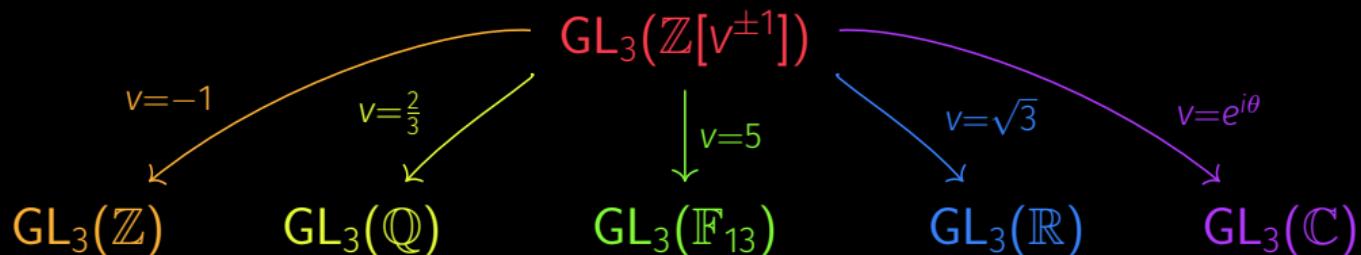
DETECTING RELATIONS

Goal: Determine if $\begin{pmatrix} -v^{-2} & -v^{-1} & 0 \\ 0 & 1 & 0 \\ 0 & -v & -v^2 \end{pmatrix}$ & $\begin{pmatrix} 0 & v^{-3} & v^{-2} \\ 0 & -v^{-2} & v^4 - v^{-1} \\ 1 & v^{-1} & 1 - v^2 \end{pmatrix}$ have a relation

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Key idea: If a relation exists, it must exist in all specialisations



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Subgoal: Detect relations between A & B in $GL_3(\mathbb{F}_{13})$

AN EXPERIMENT IN $SL_2(\mathbb{F}_{13})$

Experiment: Detect relations between A & B in $SL_2(\mathbb{F}_{13})$

Method: Use the natural action $SL_2(\mathbb{F}_{13}) \curvearrowright \mathbb{P}^1(\mathbb{F}_{13})$

$$g = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \quad p = [x : y] \quad g \cdot p = [ax + by : cx + dy]$$

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Perm. representation: $g \mapsto P_g$ permutation matrix

$$\text{tr}(P_g) = \begin{cases} 14 & \text{if } g = \pm \begin{pmatrix} 1 & \\ & 1 \end{pmatrix} \\ 0, 1, 2 & \text{otherwise} \end{cases} \quad \rightsquigarrow \quad \text{tr}(P_g) \text{ detects if } g \text{ is the identity}$$

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$$\text{tr}(P_g^{\otimes 3}) = \begin{cases} 14^3 & \text{if } g = \pm \begin{pmatrix} 1 & \\ & 1 \end{pmatrix} \\ 0^3, 1^3, 2^3 & \text{otherwise} \end{cases} \rightsquigarrow \begin{aligned} \text{tr}(P_g^{\otimes 3}) \text{ detects if } \\ g \text{ is the identity} \end{aligned}$$

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AN EXPERIMENT IN $\mathrm{SL}_2(\mathbb{F}_{13})$

Experiment: Detect relations between A & B in $\mathrm{SL}_2(\mathbb{F}_{13})$

$$(P_A + P_{A^{-1}})(P_B + P_{B^{-1}}) = P_{AB} + P_{AB^{-1}} + P_{A^{-1}B} + P_{A^{-1}B^{-1}}$$

$$((P_A + P_{A^{-1}})(P_B + P_{B^{-1}}))^2 = P_{ABAB} + P_{ABAB^{-1}} + P_{ABA^{-1}B} + P_{ABA^{-1}B^{-1}} + \dots$$

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⋮

$$((P_A + P_{A^{-1}})(P_B + P_{B^{-1}}))^{\ell} = \sum_{\substack{\text{words } W \\ \text{length}=2\ell}} P_W$$

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⋮

$$\mathrm{tr}(((P_A + P_{A^{-1}})(P_B + P_{B^{-1}}))^\ell) = \sum_{\substack{\text{words } W \\ \text{length}=2\ell}} \mathrm{tr}(P_W)$$

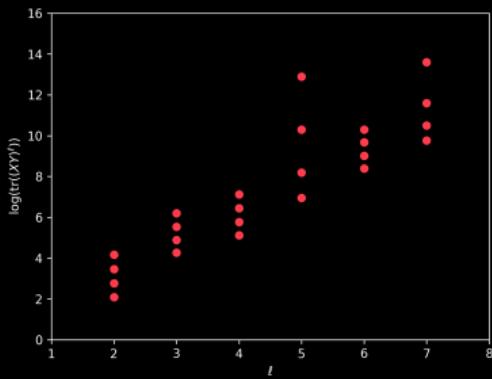
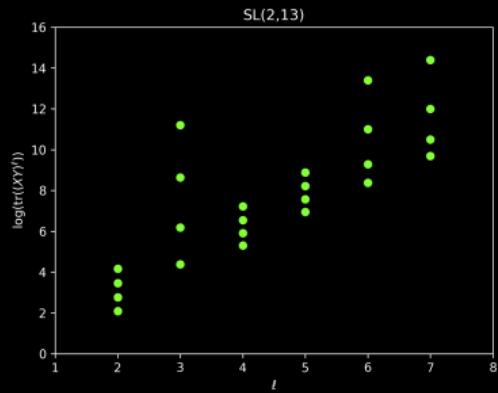
AN EXPERIMENT IN $\mathrm{SL}_2(\mathbb{F}_{13})$

$$A = \begin{pmatrix} 2 & 0 \\ 12 & 7 \end{pmatrix}$$

$$B = \begin{pmatrix} 6 & 3 \\ 10 & 3 \end{pmatrix}$$

$$A = \begin{pmatrix} 8 & 4 \\ 8 & 9 \end{pmatrix}$$

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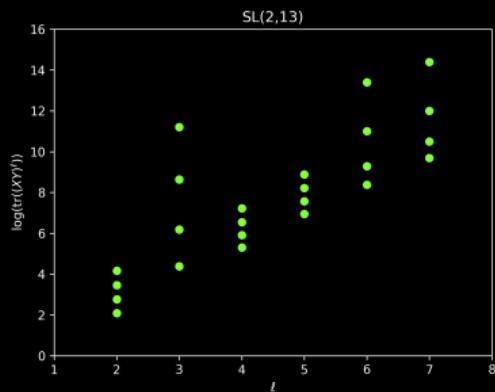
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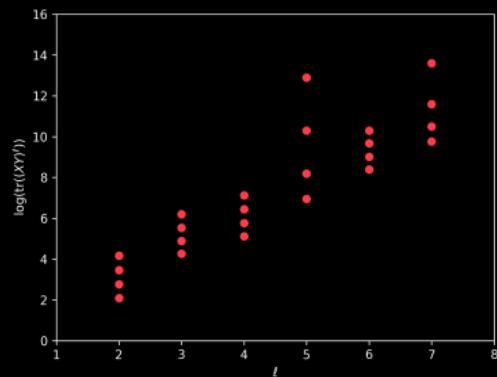
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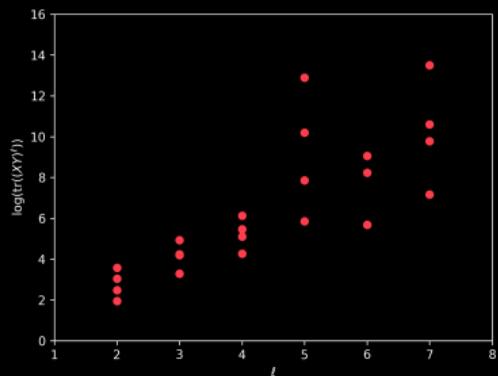
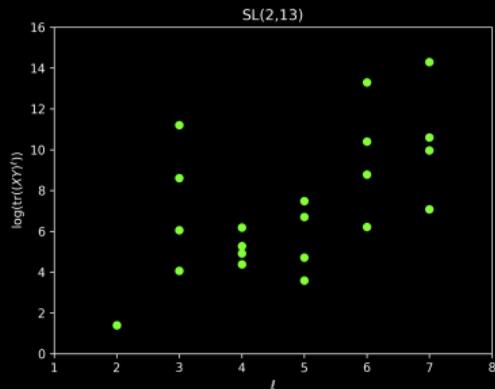
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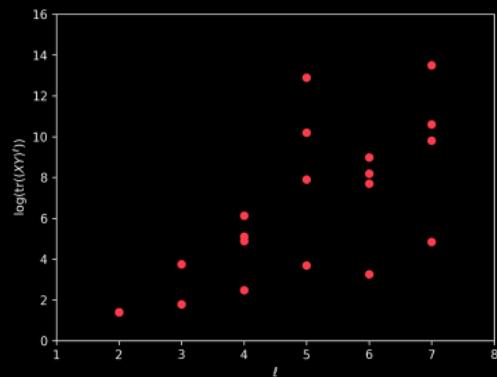
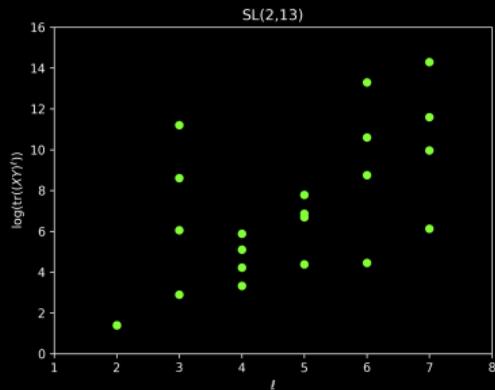
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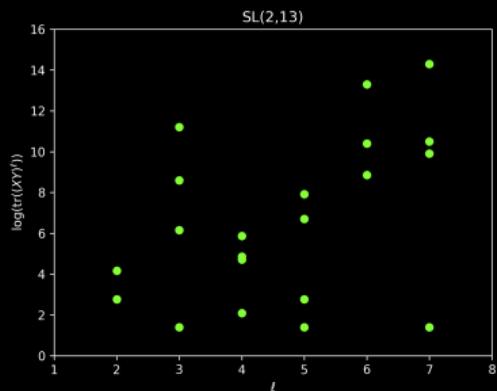
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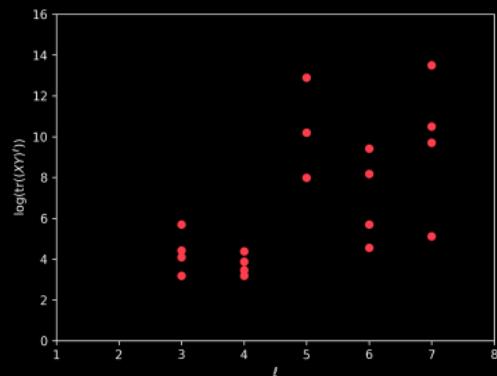
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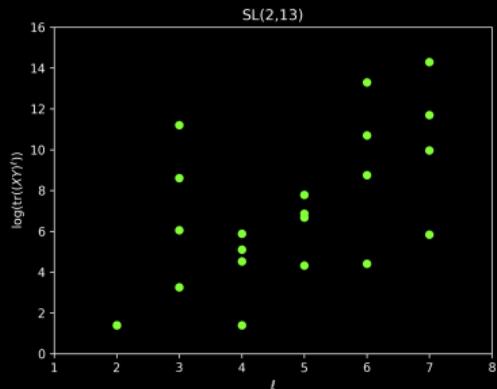
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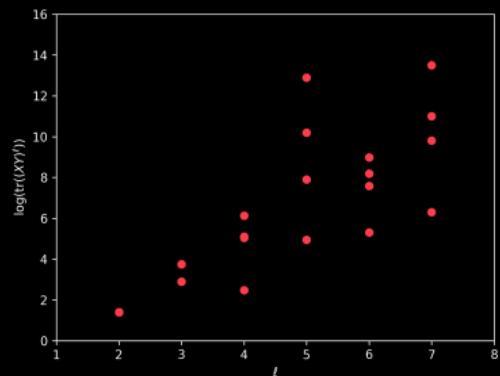
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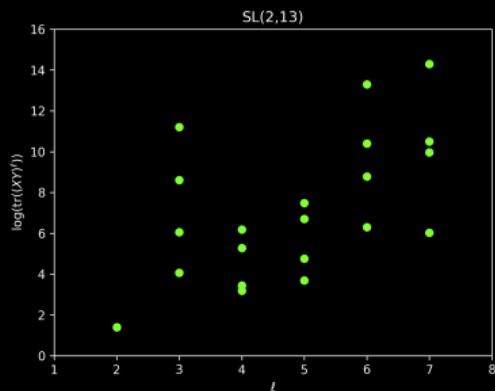
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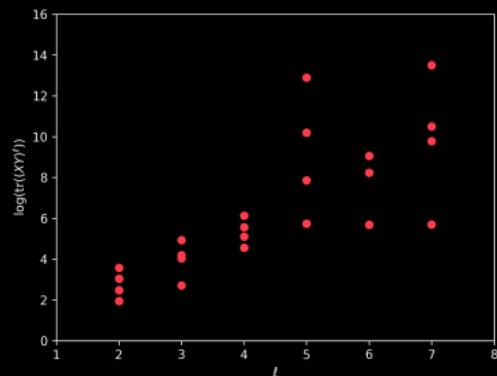
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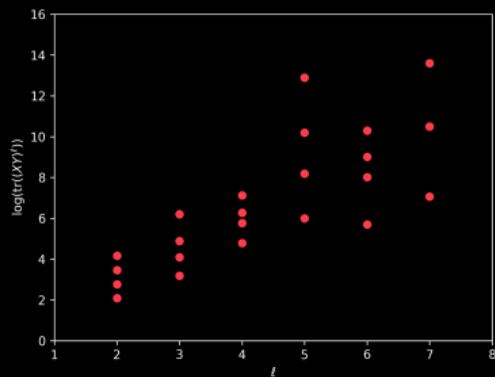
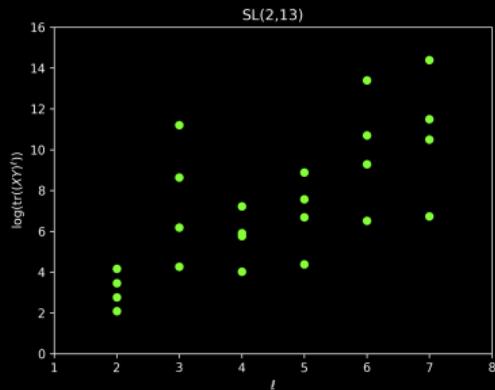
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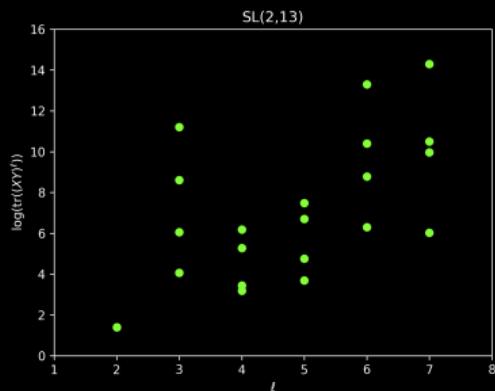
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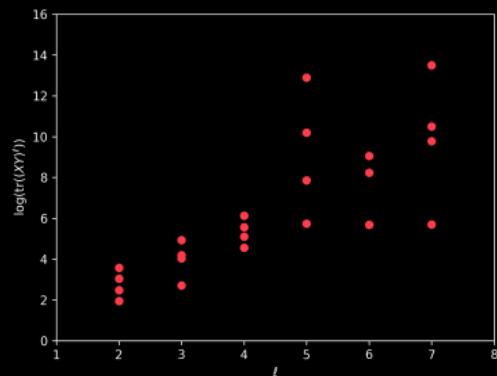
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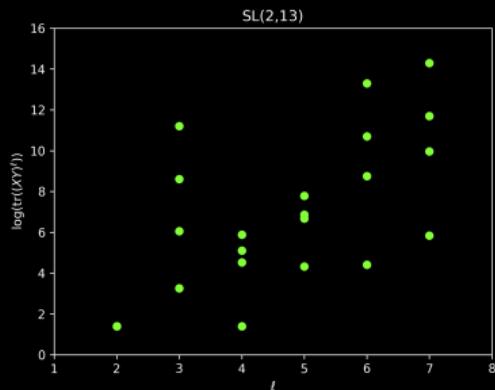
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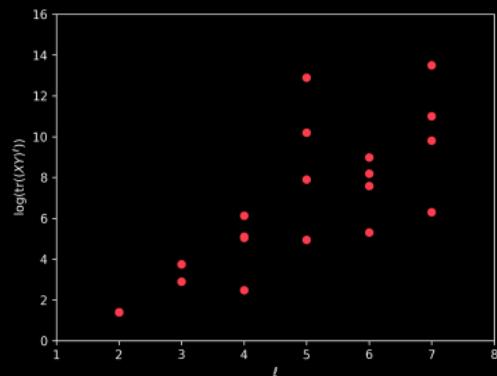
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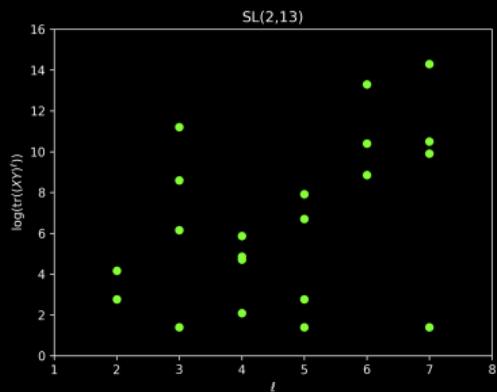
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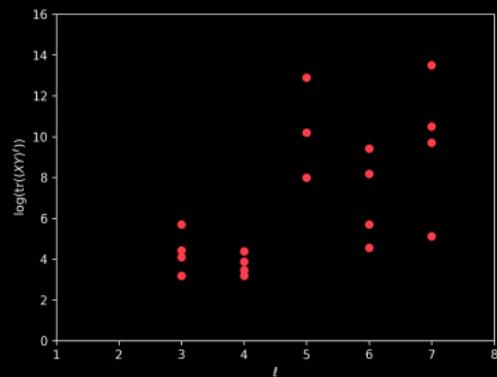
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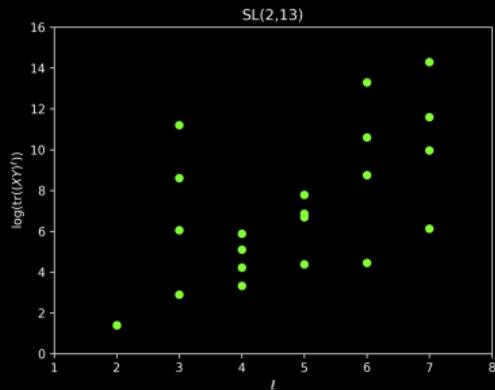
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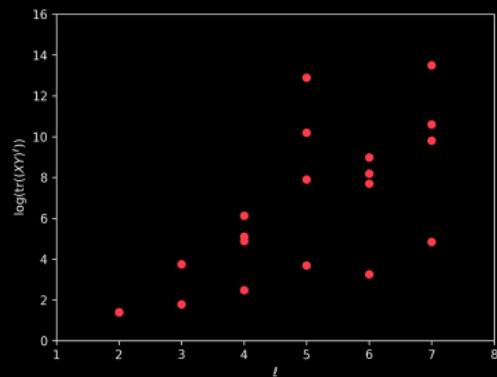
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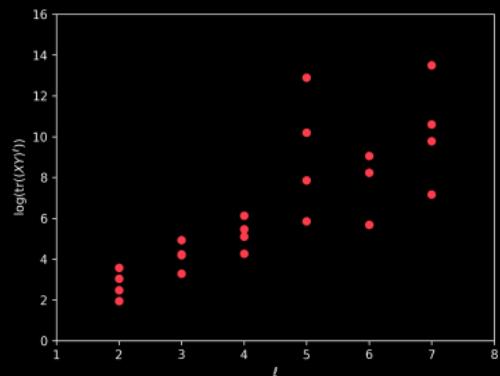
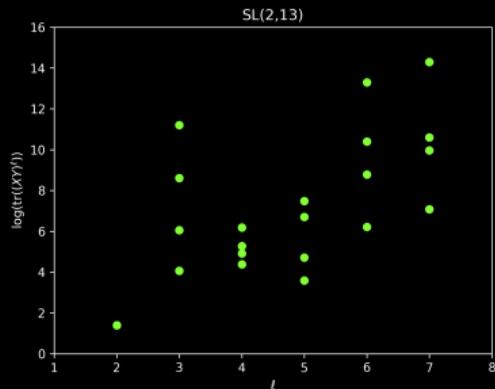
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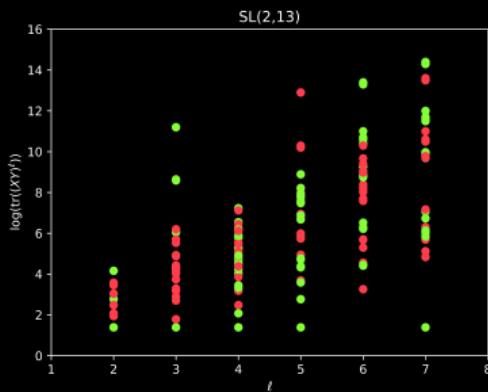
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